

# **University of Stuttgart** Institute of Engineering Geodesy

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## **Overall Project Goals**

Development of a methodology for the efficient detection and localization of track faults



**ConMoRAIL - Efficient** Sensor-Based **Condition Monitoring** Methodology for the **Detection and** Localization of Faults on the Railway Track

- Development of a cost-effective, boardautonomous and permit-free monitoring system
- **Geodetic contribution:** 
  - Development of a kinematic sensor fusion algorithm by Extended/Unscented Kalman Filter
  - Design and implementation of data model and relational database for digital track map
- **Project partners:** Institute of Engineering Geodesy (IIGS), University of Stuttgart; Institute of Railway and Transportation Engineering (IEV), University of Stuttgart

## Approach

 Low-Cost GNSS and IMU data acquisition while mounted on a regular train

#### **Digital Track Map**

- Design and implementation of a data model and a relational database
- Expansion of the database with spatio-temporal attributes (e.g. average speeds)
- Further attributes for infrastructure and defect classifications
- Integration of detected and classified track faults into the map
- Additional meta data regarding the quality of the stored map elements (e.g. accuracy, up-todateness) must be foreseen







https://www.asc-sensors.de/sensoren/asc-imu-7-ln/

https://www.u-blox.com/en/product/ann-mb-series



https://www.ni.com/de-de/shop/model/crio-9042.html

- Sensor Fusion using Extended/Unscented Kalman Filter
- Matching train position to map
- Integration of the digital track map into the algorithm as stochastic equality and inequality constraints

**GNSS** Antenna



#### **Selected Publications**

Lerke, O., Bahamon-Blanco, S., Metzner, M., Martin, U., Schwieger, V. (2021): Vorarbeiten zur Entwicklung eines Gleisfehlerdetektionssystems mit Regelzügen und Low-Cost Sensorik. ZfV, Vol. 146, No. 3 (2021). https://doi.org/10.12902/zfv-0339-2021

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